AMENDMENTS TO THE CLAIMS

Docket No.: 09656/0204589-US0

This listing of claims replaces all prior claims, and listings of claims, in the application:

**Listing of Claims:** 

Claim 1 (Currently Amended): An image configuring apparatus comprising:

an object image configuring means, which reads image data of a plurality of reduced object images from a reduced image recording means for recording image data of a plurality of reduced object images obtained by photographing an object as using a compound-eye camera that focuses a

plurality of reduced object images on a photo detector through micro lens array having a plurality of

micro lenses arrayed therein, and configures a single object image based on said image data and

then outputs its image data,

wherein said object image configuring apparatus is also configured that said micro lens and said light receiving elements are set without alignment error, and preset in the conditions including

the distance between object and micro lens array, using the aligning distance of each micro lens of

lens array and the focal length of micro lens array, and based on such presetting condition, the

magnification ratio of reducing optical system is calculated with the known distance to the object, and by obtaining the relation among one pixel of the reduced image element and its corresponding

area of the object, and previously obtain the geometric transfer function  $T_k$  describing optical

projection from the said real object to create said reduced image element and inverse transfer

function  $T_k^{-1}$ ;

wherein said object image configuring means comprising:

a generating means of initial object image for generating an initial image data of a single

object image based on an image data of a plurality of said reduced object images captured by said

micro lens array under said known condition using said inverse transfer function  $T_k^{-1}$ ;

a reduced image estimating means for estimating an estimated image of each of said reduced

object images from an image data of a provided single object image which comes from said

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generating means of initial object image, based on a geometric projection process where said

transfer function T<sub>k</sub> is used;

an object image updating means for updating an image data of said single object image

provided in said reduced image estimating means by projecting a difference between said estimated

image of each reduced object images which comes from said reduced image estimating means and

each of said reduced object images which is captured under said known condition of micro lens

<u>array</u>, in an <u>using said</u> inverse process  $T_k^{-1}$  of said geometric projection process; and

an iterative control means for firstly giving said initial image data to said reduced image

estimating means as an initial value of an image data of said single object image, and then

repetitively conducting [[a]] an estimating processing of said reduced image estimating means as

well as [[a]] an updating processing of said object image updating means until said difference

satisfying a predetermined condition, then outputting an image data of said single object image at

the time of said difference satisfying said predetermined condition as a final image data of an object

image.

Claim 2 (Original): An image configuring apparatus according to Claim 1, wherein said

object image configuring means further comprises a shift amount calculating means for calculating

a shift amount in regard to a gap of relative positions between said reduced object images through

correlation calculation between said reduced object images by using an image data of a plurality of

said reduced object images.

Claim 3 (Original): An image configuring apparatus according to Claim 2, wherein said

object image configuring means further comprises a projection process deriving means for

obtaining a conversion equation indicating said geometric projection process employed in said

reduced image estimating means based on said shift amount obtained in said shift amount

calculating means.

Claim 4 (Previously Presented): An image configuring apparatus according to Claim 2,

wherein said generating means of initial object image in said object image configuring means

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generates an image data of a single object image by arranging a plurality of said reduced object

images onto a same area based on said shift amount obtained in said shift amount calculating

means, and then generates an initial image data of said single object image by interpolating blank

pixels with respect to said image data.

Claim 5 (Currently Amended): An image configuring method for configuring a single

object image based on an image data of a plurality of reduced object images obtained by

phpotographing photographing an object as using a compound-eye camera that focuses a plurality

of reduced object images on a photo detector through micro lens array having a plurality of micro

lenses arrayed therein, comprising the steps of:

generating an initial image data of a single object image based on an image data of a

plurality of said reduced object images using known conditions and an inverse transfer function T<sub>k</sub><sup>z</sup>

<u>1</u>;

estimating an estimated image of each of said reduced object images from an image data of

a provided single object image based on a geometric projection process using a transfer function T<sub>k</sub>;

updating an image data of said single object image provided in said reduced image

estimating process by projecting a difference between estimated images of each of said reduced

object images and each of said reduced object images in an inverse process  $(T_k^{-1})$  of said geometric

projection process; providing said initial image data to said reduced image estimating process as an

initial value of an image data of said single object image;

repetitively conducting said reduced image estimating process as well as said object image

updating process until said difference satisfying a predetermined condition; and

outputting an image data of said single object image at the time of said difference satisfying

said predetermined condition as a final image data of an object image.

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